

**Academic lesson plan for summer semester - 2024**

Name of the Teaching faculty: KISHORE CHANDRA PRUSTY  
 Semester: 6<sup>th</sup>  
 No. of periods per week: 5  
 semester Exam: 80  
 Total Marks: 100

Discipline / Dept.: EE  
 Subject (Theory): CSE  
 Total Periods: 75  
 Class Test: 20

Week	Period	UNIT/CHAPTER	Topic to be covered
1 <sup>ST</sup>	1 <sup>st</sup>	FUNDAMENTAL OF CONTROL	Introduction to CS. Classification of Control system
	2 <sup>nd</sup>	FUNDAMENTAL OF CONTROL	Open loop & Closed loop system and its comparison
	3 <sup>rd</sup>	FUNDAMENTAL OF CONTROL	Effects of Feed back
	4 <sup>th</sup>	FUNDAMENTAL OF CONTROL	Standard test Signals. Servomechanism
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Discussion about different test signals.
2 <sup>ND</sup>	1 <sup>st</sup>	MATHEMATICAL MODEL OF A	Transfer Function & Impulse response
	2 <sup>nd</sup>	MATHEMATICAL MODEL OF A	Properties, Advantages & Disadvantages of T.F
	3 <sup>rd</sup>	MATHEMATICAL MODEL OF A	Poles & Zeroes of T.F. Problems Dis TF of network.
	4 <sup>th</sup>	MATHEMATICAL MODEL OF A	Mathematical modeling of Electrical Systems.
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Discussion of formulas of Laplace Transform.
3 <sup>RD</sup>	1 <sup>st</sup>	CONTROL SYSTEM COMPONENTS	Components of Control System
	2 <sup>nd</sup>	CONTROL SYSTEM COMPONENTS	Gyroscope, Synchros,
	3 <sup>rd</sup>	CONTROL SYSTEM COMPONENTS	Tachometer, DC servomotors
	4 <sup>th</sup>	CONTROL SYSTEM COMPONENTS	Ac Servomotors
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Simple Problem Discussion on Laplace Transform
4 <sup>TH</sup>	1 <sup>st</sup>	BLOCK DIAGRAM ALGEBRA	Basic Elements of Block Diagram
	2 <sup>nd</sup>	BLOCK DIAGRAM ALGEBRA	Canonical Form of Closed loop Systems
	3 <sup>rd</sup>	BLOCK DIAGRAM ALGEBRA	Rules for Block diagram reduction
	4 <sup>th</sup>	BLOCK DIAGRAM ALGEBRA	Procedure for Reduction of Block Diagram
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Examples problems of Block Diagram reduction
5 <sup>TH</sup>	1 <sup>st</sup>	BLOCK DIAGRAM ALGEBRA	Problem for equivalent transfer function
	2 <sup>nd</sup>	SIGNAL FLOW GRAPHS	Signal Flow Graph & properties
	3 <sup>rd</sup>	SIGNAL FLOW GRAPHS	Construction of SFG from Block diagram
	4 <sup>th</sup>	SIGNAL FLOW GRAPHS	Mason's Gain formula. problems on Signal flow graph
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Examples problems of Signal Flow Graph
6 <sup>TH</sup>	1 <sup>st</sup>	TIME RESPONSE ANALYSIS	Time response of control system
	2 <sup>nd</sup>	TIME RESPONSE ANALYSIS	Standard Test signal
	3 <sup>rd</sup>	TIME RESPONSE ANALYSIS	Time Response of 1 <sup>st</sup> order system with Unit step res.
	4 <sup>th</sup>	TIME RESPONSE ANALYSIS	Time Response of 1 <sup>st</sup> order system with Unit impulse res
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Simple Problem Discussion on Time Response Analysis
7 <sup>TH</sup>	1 <sup>st</sup>	TIME RESPONSE ANALYSIS	Time response of 2 <sup>nd</sup> order system to the unit step input
	2 <sup>nd</sup>	TIME RESPONSE ANALYSIS	Time response of 2 <sup>nd</sup> order system to the unit step input
	3 <sup>rd</sup>	TIME RESPONSE ANALYSIS	Types of errors in control system
	4 <sup>th</sup>	TIME RESPONSE ANALYSIS	Types of errors in control system
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Simple Problem Discussion on Time Response Analysis.
8 <sup>TH</sup>	1 <sup>st</sup>	TIME RESPONSE ANALYSIS	Effect of adding poles and zero to transfer function
	2 <sup>nd</sup>	TIME RESPONSE ANALYSIS	Response with P, PI, PD and PID controller
	3 <sup>rd</sup>	ROOT LOCUS TECHNIQUE	Root locus concept
	4 <sup>th</sup>	ROOT LOCUS TECHNIQUE	Routh hurwitz criterion
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Examples problems of Routh hurwitz criterion
9 <sup>TH</sup>	1 <sup>st</sup>	ROOT LOCUS TECHNIQUE	Construction of root loci
	2 <sup>nd</sup>	ROOT LOCUS TECHNIQUE	Rules for construction of the root locus with example
	3 <sup>rd</sup>	ROOT LOCUS TECHNIQUE	Rules for construction of the root locus with example
	4 <sup>th</sup>	ROOT LOCUS TECHNIQUE	Effect of adding poles and zeros to G(s) and H(s)
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Objective questions on basics of Control System
10 <sup>TH</sup>	1 <sup>st</sup>	ROOT LOCUS TECHNIQUE	Examples problems of Root locus Diagram
	2 <sup>nd</sup>	ROOT LOCUS TECHNIQUE	Examples problems of Root locus Diagram
	3 <sup>rd</sup>	ROOT LOCUS TECHNIQUE	Examples problems of Root locus Diagram
	4 <sup>th</sup>	ROOT LOCUS TECHNIQUE	Examples problems of Root locus Diagram

	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Objective questions on basics of Control System
11 <sup>TH</sup>	1 <sup>st</sup>	FREQUENCY RESPONSE OF SYSTEM	Correlation between time & frequency response
	2 <sup>nd</sup>	FREQUENCY RESPONSE OF SYSTEM	Polar plots
	3 <sup>rd</sup>	FREQUENCY RESPONSE OF SYSTEM	Bode plots.
	4 <sup>th</sup>	FREQUENCY RESPONSE OF SYSTEM	All pass and minimum phase system
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Objective questions on basics of Control System
12 <sup>TH</sup>	1 <sup>st</sup>	FREQUENCY RESPONSE OF SYSTEM	Computation of Gain margin and phase margin
	2 <sup>nd</sup>	FREQUENCY RESPONSE OF SYSTEM	Log magnitude versus phase plot.
	3 <sup>rd</sup>	FREQUENCY RESPONSE OF SYSTEM	Closed loop frequency response
	4 <sup>th</sup>	FREQUENCY RESPONSE OF SYSTEM	Examples problems of Bode Plot
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Objective questions on basics of Control System
13 <sup>th</sup>	1 <sup>st</sup>	FREQUENCY RESPONSE OF SYSTEM	Examples problems of Bode Plot
	2 <sup>nd</sup>	FREQUENCY RESPONSE OF SYSTEM	Examples problems of Bode Plot
	3 <sup>rd</sup>	NYQUIST PLOT	Principle of argument
	4 <sup>th</sup>	NYQUIST PLOT	Niquist stability criterion
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Objective questions on basics of Control System
14 <sup>th</sup>	1 <sup>st</sup>	NYQUIST PLOT	Niquist stability criterion applied to inverse polar plot
	2 <sup>nd</sup>	NYQUIST PLOT	addition of poles and zeros to G(S) H(S)
	3 <sup>rd</sup>	NYQUIST PLOT	Effect on the shape of Nyquist plot by pole zero addition
	4 <sup>th</sup>	NYQUIST PLOT	Assessment of relative stability
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Doubts of Control System.
15 <sup>th</sup>	1 <sup>st</sup>	NYQUIST PLOT	Constant M and N circle
	2 <sup>nd</sup>	NYQUIST PLOT	Nicholas chart.
	3 <sup>rd</sup>	NYQUIST PLOT	Examples problems of Nyquist Plot
	4 <sup>th</sup>	NYQUIST PLOT	Examples problems of Nyquist Plot
	5 <sup>th</sup>	TUTORIAL CUM DOUBT CLEAR	Doubts of Control System.

The lesson plan prepared by the concerned faculty.

KISHORE CHANDRA PRUSTY  
GF, ELECTRICAL DEPARTMENT